

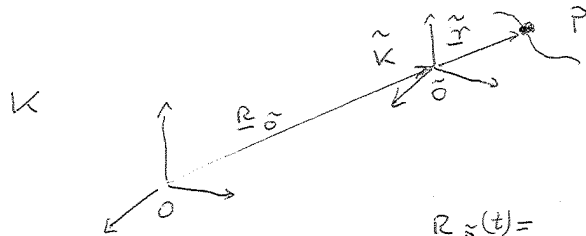
Relativistic mechanics

Galilei: • frame of reference
 origin O
 3 directions $(\underline{e}_1, \underline{e}_2, \underline{e}_3)$ } space
 + time t

• inertial frame of reference
 in these frames objects are at rest or follow straight lines unless force acts on them

- inertial frames move along straight lines w.r.t. each other

- transformation of coordinates (Galilei)



$$\underline{r}_{\tilde{O}}(t) = \underline{r}_O + \underline{W} \cdot t, \quad (*)$$

$$\underline{\tilde{r}}(t) + \underline{r}_{\tilde{O}}(t) = \underline{r}(t)$$

⇒ velocity

transformation / addition

$$\underline{v} = \underline{\tilde{v}} + \underline{W} \quad (**)$$

• Relativity:

no way to tell which frame (inertial) moves ...

Maxwell:

in vacuum

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \Delta \right) \underline{E} = \underline{\phi} \quad (***)$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

light moves with velocity c ...

contradiction:

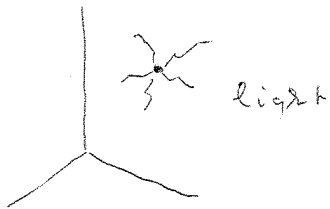
Case A: (X) is correct \Rightarrow (X*) can work in a single frame of reference \equiv ETHER
a single inertial frame of reference

Case B: (X*) is correct \Rightarrow (X) is wrong...

Tests: • Michelson - Morley (1887)
 \Rightarrow no ether

light propagates in any inertial frame of reference with velocity c , along straight line

Lorentz - Einstein



$$dx^2 = c^2 dt^2$$

$$d\tilde{x}^2 = c^2 d\tilde{t}^2$$

\Rightarrow

$$c^2 dt^2 - dx^2 \equiv ds^2$$

invariant!

Generalize Galilei transformation

"event" = "now and here" = $\{x^M\} \equiv (ct, \underline{x}) \equiv X$

four vector $M=0,1,2,3$

$$\Rightarrow \tilde{X} \equiv \{\tilde{x}^M\} = (c\tilde{t}, \tilde{\underline{x}}) = ?$$

map must be linear! (image of straight line is straight line!)

$$\tilde{x}^M = \sum_{\nu} L^M_{\nu} x^{\nu} + a^M$$

Lorentz transformation

$$\tilde{X} = A + L \cdot X$$

Poincaré

introduce metric tensor $G \equiv \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix} \equiv \{g^{\mu\nu}\} \equiv \{g_{\mu\nu}\}$

$$ds^2 = dX^T G dX \stackrel{!}{=} d\tilde{X}^T G d\tilde{X} = dX^T L^T G L dX$$

$$G = L^T G L$$

\Leftrightarrow orthogonal matrices
 $\mathbb{1} = O^T O$

defines a group: $O(3,1)$ or $O(1,3)$

Lorentz group: $L \in \mathfrak{L}$

$$L_1 \text{ and } L_2 \in \mathfrak{L} \Rightarrow L_1 L_2 \in \mathfrak{L}$$

$$L_1^{-1}, L_2^{-1} \in \mathfrak{L}$$

take 2×2 $O(1,1)$ case:

$$L_2 = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \quad g_2 = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$$

$$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} \alpha^2 - \beta^2 & \alpha\beta - \gamma\delta \\ \dots & \beta^2 - \delta^2 \end{pmatrix} = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$$

$$\alpha \equiv \cosh \varphi \quad \begin{matrix} \sigma_z \\ \parallel \\ \pm 1 \end{matrix}$$

$$\gamma \equiv -\sinh \varphi$$

$$\delta \equiv \sigma_x \cdot \cosh \vartheta$$

$$\beta \equiv -\sinh \vartheta$$

case $\sigma_z = \sigma_x = 1 \Rightarrow \vartheta = \varphi$

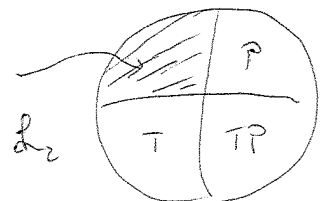
$$L_2(\varphi) = \begin{pmatrix} \cosh \varphi & -\sinh \varphi \\ -\sinh \varphi & \cosh \varphi \end{pmatrix} \sim \text{rotation in hyperbolic space!}$$

parity: $P \equiv \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}; \quad T \equiv \begin{pmatrix} -1 & \\ & 1 \end{pmatrix}$
 \uparrow time reversal

$$\mathfrak{L}_2 = \left\{ L_2(\varphi), P L_2(\varphi), T L_2(\varphi), P T L_2(\varphi) \right\}$$

ordinary L-transformations

\sim subgroup



identify φ

$$(1) \quad c\tilde{t} = ct \cdot \text{ch}(\varphi) - x \cdot \text{sh}(\varphi)$$

$$(2) \quad \tilde{x} = -\text{sh}(\varphi) \cdot ct + x \cdot \text{ch}(\varphi)$$

origin $\tilde{0}$: $\tilde{x} = 0 \Rightarrow x = \underbrace{c \cdot \text{th}(\varphi)}_w \cdot t$

$$\text{ch}^2(\varphi) = \frac{1}{1 - \text{th}^2(\varphi)} = \frac{1}{1 - w^2/c^2} \Rightarrow \text{sh}^2(\varphi) = \frac{w^2/c^2}{1 - w^2/c^2}$$

$$\Rightarrow \left[\tilde{t} = \frac{t - \frac{w}{c^2} x}{\sqrt{1 - w^2/c^2}} \right], \left[\tilde{x} = \frac{x - w \cdot t}{\sqrt{1 - w^2/c^2}} \right]$$

Inverse:

$$L_2(\varphi_1) \cdot L_2(\varphi_2) = L_2(\varphi_1 + \varphi_2) \Rightarrow$$

$$(L_2(\varphi))^{-1} = L_2(-\varphi) \Rightarrow w \leftrightarrow -w !$$

velocity addition:

invert $(t+z)$
($\varphi \rightarrow -\varphi$)

$$dt = d\tilde{t} \cdot \gamma + \frac{d\tilde{x}}{c} \cdot S$$

$$dx = +S \cdot c d\tilde{t} + c \cdot d\tilde{x}$$

$$\Rightarrow \left[v_p = \frac{dx}{dt} = \frac{S \cdot c dt + c d\tilde{x}}{c dt + \frac{d\tilde{x}}{c} \cdot S} = \frac{w + \tilde{v}_p}{1 + \frac{\tilde{v}_p \cdot w}{c^2}} \right]$$

• $c \rightarrow \infty \quad \checkmark$

• $\tilde{v}_p = c$ (light) $\rightarrow v_p = c \quad \checkmark$

Physical consequences:

• time dilation:

"proper time" in \tilde{K} $\quad d\tilde{x} = 0 \quad d\tilde{\tau} = d\tilde{t}$
 start clock and wait first tick $\rightarrow d\tilde{\tau}$

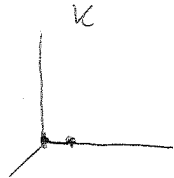
\Rightarrow in K : $dt = \cosh(\varphi) \cdot d\tilde{t} + \beta = \frac{d\tilde{\tau}}{\sqrt{1 - w^2/c^2}}$
 $dx = \beta + \sinh(\varphi) \cdot c \cdot d\tilde{t}$

$dt > d\tilde{\tau}$!

- tests:
 - μ -on short lived particle (lepton) \rightarrow detected on earth
 - supersonic airplanes + atomic clocks!
 - Alvager et al (CERN) $\pi^0 \rightarrow \gamma \gamma$
 1964 $w \approx c$ $\uparrow \uparrow$ move with c

• Lorentz-contraction

distance \sim equal time measurement,



"orbit"

\Rightarrow ends of standing rod in \tilde{K}

$\tilde{x}_1 = 0 \quad \tilde{x}_2 = \tilde{L}$

moves in K !

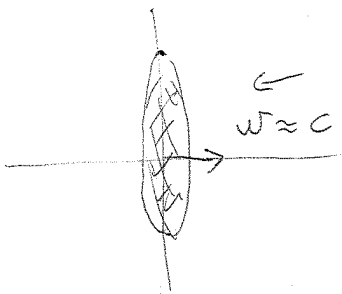
$\tilde{x}_1 = 0 = \frac{x_1 - w \cdot t_1}{\sqrt{1 - w^2/c^2}}, \quad \tilde{x}_2 = \tilde{L} = \dots$

measure distance at given time $t_1 \equiv t_2 \equiv \beta$, e.g.

$\Rightarrow x_1 = 0 \quad x_2 = \sqrt{1 - w^2/c^2} \cdot \tilde{x}_2$

$\Rightarrow L = x_2 - x_1 = \sqrt{1 - w^2/c^2} \cdot \tilde{L}$

length of moving object squeezed!



moving ball, as we observe it in case we take a picture...

Lecture 2

General case:

Lorentz group:

rotations:

$$R_z(\vartheta) = \begin{pmatrix} 1 & & & \\ & \cos\vartheta & -\sin\vartheta & \\ & \sin\vartheta & \cos\vartheta & \\ & & & 1 \end{pmatrix}, R_x, R_y$$

boosts:

$$K_x(\varphi) = \begin{pmatrix} \cosh\varphi & -\sinh\varphi & & \\ -\sinh\varphi & \cosh\varphi & & \\ & & 1 & \\ & & & 1 \end{pmatrix}, K_y, K_z$$

Remarks: $K_x(\varphi_x) K_y(\varphi_y) \neq K_y(\varphi_y) K_x(\varphi_x)$

$R_x(\vartheta_x) K_z(\varphi_z) \neq K_z(\varphi_z) R_x(\vartheta_x)$ etc.

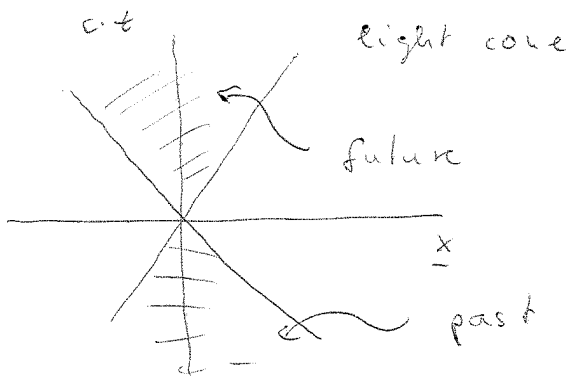
proper L-group

$\det L = 1$, $L_{00} \geq 1$

P and T \Rightarrow full L-group

symmetry of space-time includes translations
 \Rightarrow Poincaré

Minkowski space:



time-like separation
 two events have a causal relation if

$$\Delta x_{AB}^M = x_A^M - x_B^M \quad \text{time-like}$$

$$\sim ds_{AB}^2 > 0 !$$

\rightarrow invariant under L

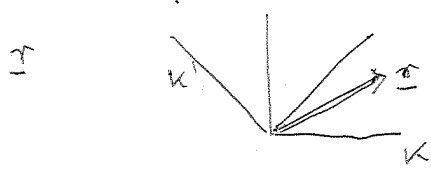
Four-vectors : covariant and contravariant representations

Def: A is a four-vector if $\alpha^M = L^M_{\nu} \alpha^{\nu}$ ↑ summation

Def: Q is a four-tensor if $\tilde{Q}^{\mu\nu} = L^{\mu}_{M'} L^{\nu}_{N'} Q^{M'N'}$

in general: $\tilde{Q}^{\mu\nu\dots\rho} = L^{\mu}_{M'} L^{\nu}_{N'} \dots L^{\rho}_{P'} Q^{M'N'\dots P'}$
 physicist's definition!

• think of rotations!



$\vec{x} \rightarrow (x^1, x^2, x^3)$ in K
 $\vec{x} \rightarrow (\tilde{x}^1, \dots, \tilde{x}^3)$ in \tilde{K}

$\tilde{x} = R x$
 orthogonal matrix

stress tensor $\hat{\sigma} \Rightarrow \sigma^{ij} = \underline{\sigma}$ in K

$\tilde{\sigma}^{ij} = \underline{\tilde{\sigma}}$ in K'

$\tilde{\sigma}^{ij} = R^i_{j'} \sigma^{j'k'} R^{k'}_{i'}$

$\tilde{\sigma} = R \sigma R^T$

A has two representations:

contravariant: $\{a^M\} = \{a^0, \underline{a}\}$
 covariant: $\{a_{\mu}\} = \{a^0, -\underline{a}\}$ } $a_{\mu} = g_{\mu\nu} a^{\nu}$

Def: scalar product:

$A \cdot B \equiv a^M b_M$

$= a^M g_{\mu\nu} b^{\nu}$
 $= a_{\nu} b^{\nu} = a_{\nu} g^{\nu\mu} b_{\mu}$

Claim: $\tilde{A} \cdot \tilde{B} = A \cdot B$

Claim: $\tilde{A} \cdot \tilde{B} = A \cdot B$

Proof: $\tilde{A} = L \cdot A$

$$\tilde{A} \cdot \tilde{B} = \tilde{A}^T G \tilde{B} = A^T \underbrace{L^T G L}_G B = A^T G B = A \cdot B \quad \square$$

Corollary: $A^2 = A \cdot A = (a^0)^2 - a^2$ is invariant!

Claim: Q is a "four"-tensor

$\text{tr } Q \equiv Q^M_M = g_{\mu\nu} Q^{\mu\nu}$ is invariant

Proof: $L^T G L = G \rightarrow g_{\mu\nu} = L^M_\mu g_{M'V'} L^{V'}_\nu$

$$\tilde{Q}^{\mu\nu} = L^M_{\mu'} L^{V'}_{\nu'} Q^{M'V'}$$

$$\text{tr } \tilde{Q} = g_{\mu\nu} \tilde{Q}^{\mu\nu} = \underbrace{g_{\mu\nu} L^M_{\mu'} L^{V'}_{\nu'}}_{g_{M'V'}} Q^{M'V'} = \text{tr } Q$$

" $g_{M'V'}$ ← L-invariant tensor!

Other similar statements:

• Q four-tensor, A a four-vector

$$\Rightarrow b^M \equiv Q^{\mu\nu} a_\nu = Q^{\mu\nu} g_{\nu\rho} a^\rho = Q^M_\rho a^\rho = \dots$$

is a four-vector

• Q has different representations:

$$Q^{\mu\nu}, Q_{\mu}{}^\nu, Q^\mu{}_\nu, Q_{\mu\nu}$$

$$- Q^{\mu\nu} = g^{\mu\rho} Q_\rho{}^\nu = g^{\mu\rho} g^{\nu\sigma} Q_{\rho\sigma}$$

$$- g^{\mu\nu} g_{\nu\rho} = g^\mu{}_\rho = \delta^\mu_\rho \Rightarrow$$

$$Q_\rho{}^\nu = g_{\rho\mu} Q^{\mu\nu}$$

$$Q^\mu{}_\rho = Q^{\mu\nu} g_{\nu\rho}$$

$g^{\mu\nu}$ and $g_{\mu\nu}$
move indices
up and down!

Def: contractions

$$T^{MNP} \dots \Rightarrow T^{M \dots} \dots \quad (n-2) \text{ - tensor}$$

n - tensor

trivial example:

$$Q^{MP} = a^M \cdot b^P$$

$$\Rightarrow Q^{\cdot} = \text{tr} Q = a^M b_M = a \cdot b \quad \text{! scalar !}$$

Principle of relativity:

- no experiment can tell, which inertial frame of reference moves ...
- \Rightarrow Laws of Nature are L-invariant
- \sim can be formulated using "four-tensors"

Momentum and energy:

Newton: force \Leftrightarrow momentum conservation!
(- mass)

↔
action - reaction

collision:
 $\exists m_1, m_2$

$$\Rightarrow \boxed{m_1 \underline{v}_1 + m_2 \underline{v}_2 = m_1 \underline{v}'_1 + m_2 \underline{v}'_2} \quad (*)$$

$$\underline{F}_{12} \equiv \frac{d}{dt}(m_2 \underline{v}_2) = - \underline{F}_{21} \equiv \frac{d}{dt}(m_1 \underline{v}_1)$$

(*) is violated by velocity addition...

$\exists?$ four-vector replacing (*)??

$\underline{v} = \frac{dx}{dt} \leftarrow$ spatial part of $dx^M \sim$ four-vector
 \leftarrow not scalar

Proper time: $c^2 d\tau^2 = c^2 dt^2 - dx^2$ ← L-invariant!

$$d\tau^2 = dt^2 \left(1 - \frac{1}{c^2} \frac{dx^2}{dt^2} \right) = dt^2 \left(1 - \frac{v^2}{c^2} \right)$$

$$d\tau = dt \sqrt{1 - v^2/c^2}$$

four-velocity: $\{U^M\} \equiv \left\{ \frac{dx^M}{d\tau} \right\} = \frac{dt}{d\tau} (c, \underline{v})$
 $\frac{1}{(1 - v^2/c^2)^{1/2}}$

$$\{U^M\} = \left(\frac{c}{\sqrt{1 - v^2/c^2}}, \frac{\underline{v}}{\sqrt{1 - v^2/c^2}} \right) \leftarrow \text{four-vector!}$$

⇒ four-momentum:

$$p^M \equiv m_0 U^M = \left(\frac{m_0 c}{\sqrt{1 - \beta^2}}, \frac{m_0 \underline{v}}{\sqrt{1 - \beta^2}} \right) =$$

rest mass

$$\{p^M\} = m (c, \underline{v})$$

relativistic mass

$$m = \frac{m_0}{\sqrt{1 - v^2/c^2}}$$

p^M is conserved!

$$p_1^M + p_2^M = p_1'^M + p_2'^M$$

energy and momentum conservation

we want to extend Newton's 3d law...

Force

$$\underline{F} = \frac{d}{dt} (m \underline{v})$$

action ~ reaction... ✓

notice:

$$\begin{aligned} \underline{F} &= \frac{d}{dt} \left(\frac{m_0}{(1 - v^2/c^2)^{3/2}} \underline{v} \right) = m \cdot \underline{\dot{v}} + \frac{m_0}{(1 - v^2/c^2)^{3/2}} \frac{\underline{v} \cdot \underline{\dot{v}}}{c^2} \underline{v} \\ &= \underbrace{m \left(1 + \frac{\underline{v} \cdot \underline{\dot{v}}}{c^2 - v^2} \right)}_{\text{mass tensor!}} \cdot \underline{\dot{v}} \end{aligned}$$

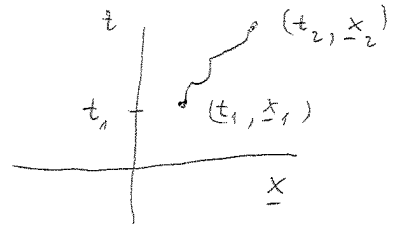
perpendicular

$$\vec{F}_\perp = \frac{m_0}{\sqrt{1-v^2/c^2}} \cdot \dot{\vec{v}}_\perp = m_\perp \dot{\vec{v}}_\perp$$

parallel

$$\vec{F}_\parallel = \frac{m_0}{(1-v^2/c^2)^{3/2}} \dot{\vec{v}}_\parallel = m_\parallel \dot{\vec{v}}_\parallel$$

Interpretation of p^0 :



$$p^2 = m_0^2 c^2 = (p^0)^2 - \vec{p}^2$$

$$\Rightarrow p^0 \dot{p}^0 = \underbrace{\vec{p} \cdot \dot{\vec{p}}}_{m \underline{v} \cdot \underline{\vec{F}}} \Rightarrow \int_{t_1}^{t_2} \dot{p}^0 dt = \Delta p^0 = \frac{1}{c} \int dt \underline{\vec{F}} \cdot \underline{v}$$

$\int dx \cdot \underline{\vec{F}} = W$

$$\Delta p^0 = p^0(t_2) - p^0(t_1) = \frac{1}{c} W_{1 \rightarrow 2}$$

$$\Rightarrow \underline{p}_0 = \frac{1}{c} E + c \vec{p}$$

$$\{p^\mu\} = \left(\frac{E}{c}, \vec{p} \right)$$

$$\Rightarrow E = c p^0 = m \cdot c^2 = \frac{m_0 c^2}{\sqrt{1-v^2/c^2}}$$

Einstein

expand $E = \underbrace{m_0 c^2}_{\text{rest energy}} + \underbrace{\frac{1}{2} m_0 v^2}_{\text{kinetic energy}} + \dots$

conservation of four-mom. \Leftrightarrow energy + momentum conservation!

energy - momentum relation:

$$p^2 = m_0^2 c^2 = \frac{E^2}{c^2} - \vec{p}^2 \Rightarrow$$

$$E = \pm \sqrt{m_0^2 c^4 + \vec{p}^2 c^2}$$

$|\vec{p}| \ll m_0 c$

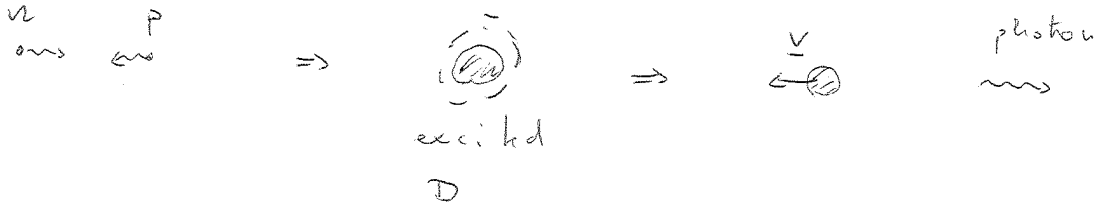
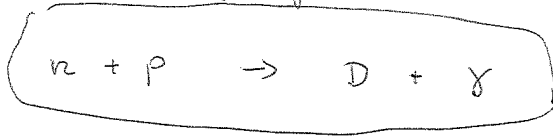
$$E = m_0 c^2 + \frac{\vec{p}^2}{2m_0} + \dots$$

$|\vec{p}| \gg m_0 c$

$E = |\vec{p}| c$
 \sim photon

Mass deficiency:

consider binding of n and p :



momentum
energy

balance
balance

$$M_D \cdot v = \hbar k$$

$$c^2 m_n^0 + c^2 m_p^0 = c^2 M_D + \hbar \omega$$

$$c^2 M_D + \frac{1}{2} M_D v^2 + \dots$$

↑
small

$$\Rightarrow c^2 m_n^0 + c^2 m_p^0 \approx c^2 M_D + \hbar \omega$$

↑
takes away binding energy!

$$M_D^0 = m_n^0 + m_p^0 + \frac{1}{c^2} \Delta E$$

binding energy $\approx -\hbar \omega$

$$\Rightarrow \underline{M_D^0 < m_n^0 + m_p^0} \quad ! \sim \text{mass deficiency}$$

Dalton

check: $m_n^0 c^2 = 1,0078 \text{ u} \cdot c^2 = 938,27 \text{ MeV} = 0,93827 \text{ GeV}$ ($10^9 \times$ chemical reaction!)

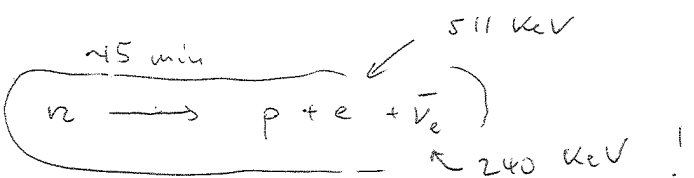
$$m_p^0 c^2 = 1,0086 \text{ u} \cdot c^2 = 938,27 \text{ MeV} = 0,93827 \text{ GeV}$$

$$M_D^0 c^2 = 2,0141 \text{ u}$$

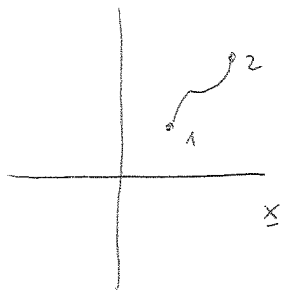
$$M_D^0 = m_p^0 + m_n^0 - 2,16 \text{ MeV}$$

Other example:

β^- decay:



Lagrangian formulation:



free particle

classical Lagrangian

$$L = \frac{m_0}{2} \dot{x}^2$$

$$S_{cl} = \int_{t_1}^{t_2} dt \frac{m_0}{2} \dot{x}^2 \Rightarrow \text{straight line}$$

$$\dot{x} = v$$

Lorentz - invariant action?

$$\Rightarrow S \sim \int_1^2 ds \sim \int_1^2 d\tau \sim \int_{t_1}^{t_2} dt \sqrt{1 - v^2/c^2}$$

$$S = -d \int dt (1 - \dot{x}^2/c^2)^{1/2} \xrightarrow[c]{d} \int_{t_1}^{t_2} \left[\frac{d}{2} \frac{\dot{x}^2}{c^2} - d(t_2 - t_1) \right]$$

$$\Rightarrow d = m_0 c^2$$

$$S = -m_0 c^2 \int dt \sqrt{1 - \dot{x}^2/c^2}$$

momentum

$$p = \frac{\partial L}{\partial \dot{x}} = \frac{m_0}{\sqrt{1 - \dot{x}^2/c^2}} \dot{x} = m \cdot v \quad (a)$$

energy:

$$\mathcal{H} = p \dot{x} - L = \frac{m_0 \dot{x}^2}{\sqrt{1 - \dot{x}^2/c^2}} + m_0 c^2 \sqrt{1 - \dot{x}^2/c^2} =$$

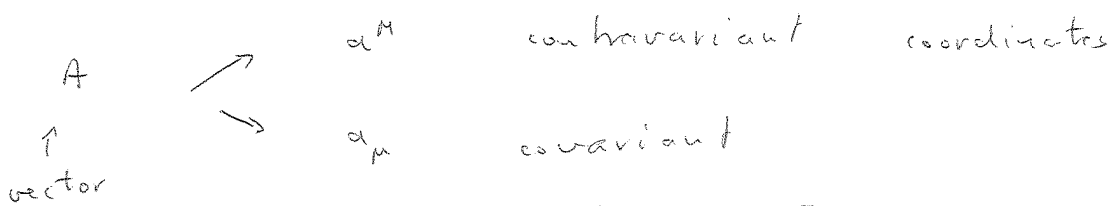
$$= \frac{m_0 \cdot c^2}{\sqrt{1 - \dot{x}^2/c^2}} \quad (b)$$

\Rightarrow invert (a) \Rightarrow (b)

$$\mathcal{H}(p) = \sqrt{c^2 p^2 + m_0^2 c^4}$$

external force?

Search for four-vectors:



L-transformation:

$$\tilde{a}^\nu = \Lambda^\nu_\mu a^\mu$$

$$\Rightarrow \tilde{a}_\nu = g_{\nu\sigma} \tilde{a}^\sigma = g_{\nu\sigma} \Lambda^\sigma_\tau a^\tau = g_{\nu\sigma} \Lambda^\sigma_\tau g^{\tau\mu} a_\mu$$

multiply by Λ^τ_ν !

$$\Lambda^\nu_\kappa \tilde{a}_\nu = \Lambda^\nu_\kappa g_{\nu\sigma} \Lambda^\sigma_\tau g^{\tau\mu} a_\mu = g_{\kappa\eta} g^{\eta\mu} a_\mu = a_\kappa$$

$\Lambda^\tau_\nu g_{\nu\sigma} \Lambda^\sigma_\tau = g_{\eta\eta} \Rightarrow g_{\eta\eta}$

$$\Rightarrow \tilde{a}_\nu = \Lambda_\nu^\mu a_\mu \quad \text{or} \quad \Lambda^\nu_\mu \tilde{a}_\nu = a_\mu$$

Statement: A is four-vector and $\exists (b_0, b_1, b_2, b_3)$

such that $A \cdot B = a^\mu b_\mu = \tilde{a}^\mu \tilde{b}_\mu$ always

$\Rightarrow \{b_\mu\}$ are covariant components of a four-vector!

Proof:

$$\tilde{a}^\mu \tilde{b}_\mu = \Lambda^\mu_\nu a^\nu \tilde{b}_\mu = a^\nu b_\nu$$

for any setup $\Rightarrow \Lambda^\mu_\nu \tilde{b}_\mu = b_\nu \checkmark$

four-wave-vector:

consider propagation of electromagnetic wave

$$\sim \sin(\omega t - \underline{k} \cdot \underline{r}) \quad \sim \text{nodes should be same for all observers!}$$

$\Rightarrow (ct, \underline{x}) \cdot \begin{pmatrix} \omega/c \\ -\underline{k} \end{pmatrix}$ is invariant (L-invariant)

$\Rightarrow \{k_\mu\} \equiv \left(\frac{\omega}{c}, -\underline{k}\right)$ is a four-vector

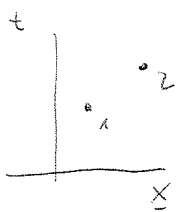
$$\{k^\mu\} = \left(\frac{\omega}{c}, \underline{k}\right)$$

$$\{k^\mu\} = \left(\frac{h\omega}{c}, \underline{h\underline{k}}\right) \quad \checkmark$$

\uparrow energy
 \uparrow momentum of photon

• differentiation ? \rightarrow gradient ??

scalar function $f(x)$ \rightarrow $f(\tilde{x}) = f(x)$



$$f(x_2) - f(x_1) = f(\tilde{x}_2) - f(\tilde{x}_1)$$

\uparrow other observer
 \uparrow me

\Downarrow

$$dx^\mu \frac{\partial f}{\partial x^\mu} = d\tilde{x}^\mu \frac{\partial f}{\partial \tilde{x}^\mu}$$

\nwarrow covariant components of a four-vector \uparrow

$$\{\partial_\mu f\} = \left\{ \frac{\partial f}{\partial x^\mu} \right\} = \left(\frac{1}{c} \frac{\partial f}{\partial t}, \underline{\nabla} f \right)$$

gradient:

$$\{\partial^\mu\} = \left(\frac{1}{c} \frac{\partial}{\partial t}, -\underline{\nabla} \right)$$

\Rightarrow scalar : $\partial^\mu \partial_\mu = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \Delta = \square$

\uparrow
d'Alembert

• Force as four-vector??

$$\underline{F} = \frac{d\underline{p}}{dt} \quad \leftarrow \text{not piece of four-vector...}$$

$$\boxed{f^M \equiv \frac{dp^M}{d\tau} = \frac{1}{\sqrt{1-v^2/c^2}} \left(\frac{1}{c} \underline{F}, \underline{F} \right)}$$

↑
four-force

↑
 \underline{F}

"conservative" force: $f^M = \partial^M U(x)$?
charged particle?

• current density:

continuity equ: $\frac{\partial \rho}{\partial t} + \text{div } \underline{j} = 0$

$$\Rightarrow \boxed{j^M \equiv (c\rho, \underline{j})} \quad \Rightarrow \boxed{\partial_\mu j^M = 0}$$

$\partial_\mu = \left(\frac{1}{c} \frac{\partial}{\partial t}, \nabla \right)$

Maxwell equations, Lorentz-force:

Maxwell:

$$\begin{aligned} \text{div } \underline{E} &= \frac{1}{\epsilon_0} \rho \\ \text{div } \underline{B} &= 0 \\ \text{rot } \underline{E} &= -\frac{\partial \underline{B}}{\partial t} \\ \text{rot } \underline{B} &= \mu_0 \underline{j} + \mu_0 \epsilon_0 \frac{\partial \underline{E}}{\partial t} \end{aligned}$$

vector potential:

$$\text{div } \underline{B} = 0 \Rightarrow \exists \underline{A} \quad \boxed{\underline{B} = \text{rot } \underline{A}}$$

measurable $\Rightarrow \text{rot} (\underline{E} + \dot{\underline{A}}) = 0 \Rightarrow \exists \phi: \quad \boxed{\underline{E} = -\text{grad } \phi - \dot{\underline{A}}}$

\downarrow
3+3 fields \Leftrightarrow 1+3 \leftarrow more fundamental
+ redundancy!

Gauge freedom:

$$\underline{A} \rightarrow \underline{A} + \text{grad } f \quad \Rightarrow \quad \underline{B} \text{ same}$$

$$\phi \rightarrow \phi - \dot{f} \quad \Rightarrow \quad \underline{E} \text{ same!}$$

$f(t, \underline{x})$ arbitrary

$$\partial^\mu f = \left(\frac{1}{c} \frac{\partial f}{\partial t}, -\text{grad } f \right) \sim \text{four-vector}$$

$$\Rightarrow \quad \boxed{A^\mu \equiv \left(\frac{1}{c} \phi, \underline{A} \right)}$$

gauge transformation:

$$A^\mu \rightarrow A^\mu - \partial^\mu f$$

A^μ generates \underline{E} and \underline{B} !

$$\boxed{F^{\mu\nu} \equiv \partial^\mu A^\nu - \partial^\nu A^\mu} \quad \Rightarrow \quad \text{tensor! contains } \underline{E}, \underline{B}$$

$$F^{0i} = \frac{1}{c} \frac{\partial A^i}{\partial t} + \frac{\partial}{\partial x^i} \frac{\phi}{c} = -\frac{1}{c} E^i$$

$$F^{ij} = -\frac{\partial A^j}{\partial x^i} + \frac{\partial A^i}{\partial x^j} \quad T^{12} = -(\text{rot } \underline{A})^3 = -B^3$$

$$\{F^{\mu\nu}\} = \begin{pmatrix} | & -\frac{1}{c} \underline{E} & | \\ \hline & -B^3 & B^2 \\ \frac{1}{c} \underline{E} & B^3 & B^1 \\ & -B^2 & B^1 \end{pmatrix} \leftarrow \underline{B} \times$$

$$\{F^{\mu}_{\nu}\} = \begin{pmatrix} | & \underline{E}/c & | \\ \hline \underline{E}/c & & -\underline{B} \times \end{pmatrix}$$

$$\partial_\mu F^{\mu\nu} = \left(\frac{1}{c} \text{div } \underline{E}, -\frac{1}{c^2} \dot{\underline{E}} + \text{rot } \underline{B} \right) = \left(\frac{1}{c} \underline{\epsilon}_0 \underline{S}, M_0 \dot{f} \right) = M_0 (\underline{S}, \dot{f})$$

$$\boxed{\partial_\mu F^{\mu\nu} = M_0 \dot{f}^\nu}$$

L - invariant action ?

$$\begin{aligned} &\sim \int d\tau \underline{v}^\mu \cdot \underline{A}_\mu = \int dx_\mu A^\mu = \\ &= \int c dt \frac{1}{c} \phi - \int d\underline{x} \cdot \underline{A} = \int dt (\phi - \dot{\underline{x}} \cdot \underline{A}) \\ &\quad \quad \quad \uparrow \\ &\quad \quad \quad \text{potential!} \end{aligned}$$

⇒

$$L(\underline{x}, \dot{\underline{x}}, t) = L \equiv -m_0 c^2 \sqrt{1 - \frac{\dot{\underline{x}}^2}{c^2}} - e \phi(\underline{x}, t) + e \dot{\underline{x}} \cdot \underline{A}(\underline{x}, t)$$

equation of motion

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\underline{x}}} = \frac{\partial L}{\partial \underline{x}}$$

$$\frac{d}{dt} \left(\frac{m_0 \dot{\underline{x}}}{\sqrt{1 - \dot{\underline{x}}^2/c^2}} + e \underline{A} \right) = -e \text{grad} \phi + e \frac{\partial}{\partial \underline{x}} (\dot{\underline{x}} \cdot \underline{A})$$

$$e \dot{A}^i + e \frac{\partial A^i}{\partial x^j} \dot{x}^j$$

$$\begin{aligned} \frac{d}{dt} (p^i) &= -e \left(\frac{\partial \phi}{\partial x^i} + \dot{A}^i \right) + e \left(\frac{\partial A^k}{\partial x^i} v^k - \frac{\partial A^i}{\partial x^k} v^k \right) \\ &= e E + e \underline{v} \times \underline{B} \quad ! \end{aligned}$$

claim:

$$\frac{dp^\mu}{dt} = q F^\mu{}_\nu v^\nu$$

homework:
prove it!

$$\mu = 0 \Rightarrow \frac{1}{c} \dot{E} = q \frac{1}{c} \underline{E} \cdot \underline{v} \quad \checkmark$$

$$\mu = 1, 2, 3 \Rightarrow \frac{d\underline{p}}{dt} = q \underline{E} - q \underline{B} \times \underline{v} \quad \checkmark$$